## Deterministic Optimization Methods For the Haplotyping Problem

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- The Haplotype Assembly Problem
- The Haplotype Inference Problem
- Tree-Grow Algorithm for Haplotype Inference Problem
- A Neural Network for the Haplotype Assembly Problem





- All humans share about 99.9% identity at the DNA level
- The differences in DNA sequences in a population are called **polymophisms**
- Such regions of variations of DNA sequences are responsible for genetics diseases and phenotype differences
- Therefore, the next important research area is to find the association relationship between DNA variations and genetic disease

- Single nucleotide polymorphism (SNP) is a single DNA base where two different nucleotides appear with sufficient frequency in a population
- SNP is the most frequent and important form among various genetic variations of DNA sequences
- SNPs are found approximately every 1000 base pairs in the human genome

The paternal copy: The maternal copy:	ATAGCCTATTCCAGGGTCGAAGAC ATAGCGTATTCCAGGGTCGTAGAC		
Haplotype $1 \rightarrow$ Haplotype $2 \rightarrow$	C G	C C	A T
Genotype →	<b>{C/G</b> }	{ <b>C</b> / <b>C</b> }	<b>{A/T</b> }

Haplotypes generally have more information content than individual SNPs and genotype in disease association studies, but it is substantially difficult to determine haplotypes through experiments

We generally have two kinds of data resource:

- short haplotype fragments (SNP fragments) from shortgun experiments
- a set of genotype information from a population

Then we have two different problems:

- Haplotype Assembly for an individual
  - Assembly a pair of haplotypes from short SNP fragments
- Haplotype Inference in a population
  - Infer haplotypes based on the genotype samples in a population

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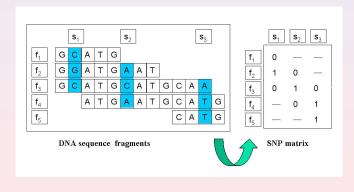
## Modeling

- Problem: Given a set of DNA fragments coming from a chromosome by a sequencing method, retrieve a pair of hapltoypes according to the SNP states in DNA fragments
- How to formulate it into a mathematical problem ( a combinatorial optimization problem)?





### From DNA fragments to SNP matrix





## Modeling

#### Conflicts come from two reasons:

- Conflict between two fragments belong to the two different copies
- Conflict between two fragments from the same copy but with experiment errors





## Modeling

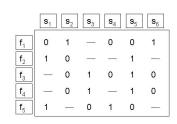
Make a graph G = (V, E),

- all fragments consist of the vertex set V
- two conflicting fragments (vertices) are connected by an edge in **E**.





## Conflict graph





SNP matrix

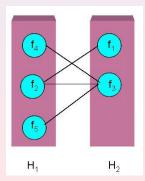


The conflict graph

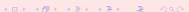


### When DNA fragments are error-free

When data has no errors, the conflict graph is a bipartite graph (a graph which can be decomposed into two disjoint sets such that no two graph vertices within the same set are adjacent)





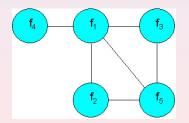


- A graph can be tested for bipartiteness using BipartiteQ in Mathematica 5.1
- A graph is bipartite if and only if it has no odd cycles (a cycle with odd number of edges) (S.Skiena, 1990)
- How to retrieve the haplotypes from data with errors 
   ⇔ How to make a graph bipartite?

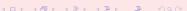




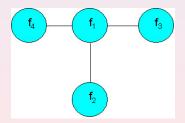
Omit some vertices to obtain a bipartite graph, that means delete some contaminated fragments







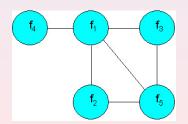
#### Omit vertices to obtain a bipartite graph







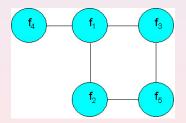
Omit edges to obtain a bipartite graph, that means remove some SNP sites or flip some SNP values







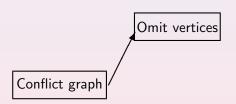
#### Omit edges to obtain a bipartite graph

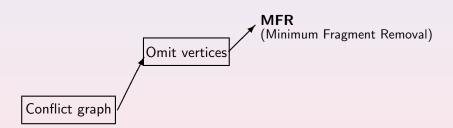


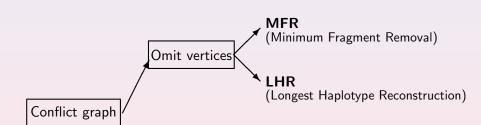


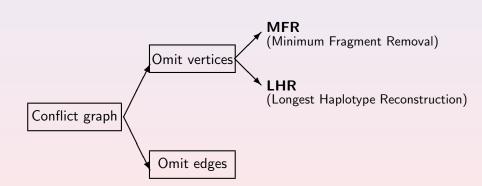


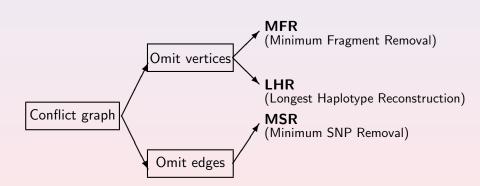
Conflict graph

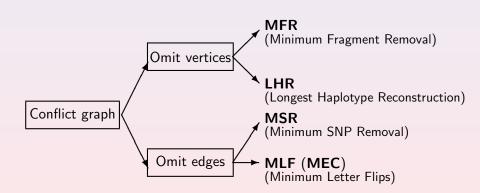


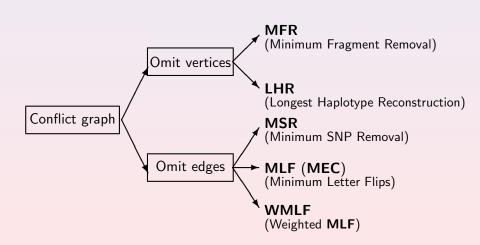












## Several combinatorial optimization models

- Cut some vertices on the odd cycles to make the remained graph bipartite:
  - remove a minimum number of fragments (rows) so that the graph is bipartite ( the resulted matrix is feasible)— MFR: Minimum Fragment Removal;
  - remove a set of fragments so that the resulted matrix is feasible and the sum of the lengths of the derived haplotypes is maximized—LHR: Longest Haplotype Reconstruction.

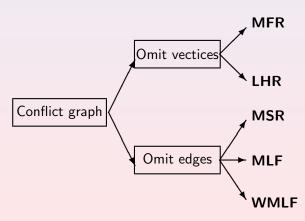


## Several combinatorial optimization models (continue)

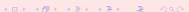
- Cut some arcs on the odd cycles to make the remained graph bipartite (the matrix feasible):
  - remove a minimum number of SNPs (columns) so that the matrix is feasible—MSR: Minimum SNP Removal;
  - flip a minimum number of site values so that the matrix is feasible— MLF: Minimum Letter Flips. Or in some papers, MEC: Minimum Error Correction.
  - Weighted MLF (WMLF): flip some letters so that the weighted sum of the flips is minimum and the resulted SNP matrix is feasible.

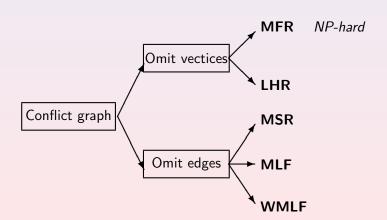






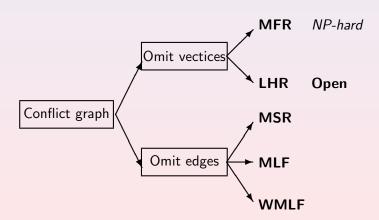




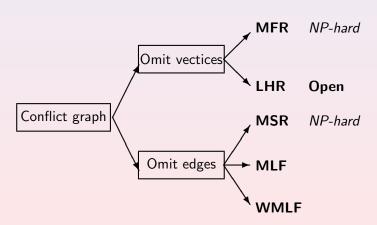






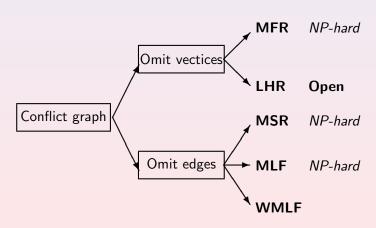






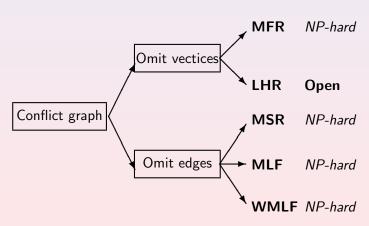
















- MFR is NP-hard even for SNP matrices in which each fragment has at most one gap
- LHR has polynomial-time algorithm when fragments are gapless, but the complexity of the general case is open
- MSR is NP-hard for SNP matrices with at most two gaps per fragment
- The general MLF (MEC) is NP-hard
- WMLF is NP-hard even if its fragments are gapless





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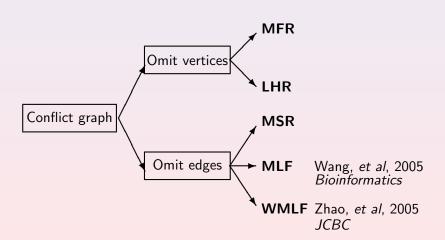
### Algorithms

- Algorithms for MFR ( Minimum Fragment Removal)
  - A dynamic programming algorithm with complexity  $O(2^{2k}m^2n + 2^{3k}n^3)$  is given by Rizzi R., *et al*, 2002, where k is the maximum number of gaps in the fragments.
- Algorithms for MSR ( Minimum SNP Removal)
  - A dynamic programming algorithm with complexity  $O(mn^{2k+2})$  is given by Rizzi R., et al, 2002.

### Algorithms (continue)

- Algorithms for **MLF** (**MEC**) (*Minimum Letter Flips, Minimum Error Correction*).
  - An exact algorithm based on branch-and-bound method and a heuristic method based on genetic algorithm (GA) are proposed to solve MEC in Wang R.-S., et al, 2005.
- Algorithms for WMLF ( Weighted MLF)
  - A heuristic algorithm based on dynamic clustering method is presented in Zhao Y.-Y et al, 2005 for WMLF.

## Our group's work:



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### Modeling

- A haplotype **h** is a vector  $(h_1, \dots, h_n)$  over  $\{0, 1\}^n$ .
- A genotype **g** is a vector  $g_1, \dots, g_n$  over  $\{0, 1, 2\}^n$ .
- A pair of haplotypes (h<sup>1</sup>, h<sup>2</sup>) is called compatible with a g if

$$h_i^1 = h_i^2 = g_i = \begin{cases} 0, & h_i^1, h_i^2 \text{ are wild} \\ 1, & h_i^1, h_i^2 \text{ are mutant,} \end{cases}$$

 $h_i^1 \neq h_i^2 \Leftrightarrow g_i = 2$ , the *i*th SNP site is heterozygous.



### Modeling

• The haplotype inference problem is:

Given a set of genotypes G, find a set of haplotypes H, such that for every genotype  $\mathbf{g} \in G$ , there exists at least one pair of haplotypes in H which are compatible this genotype.





#### Several versions for haplotype inference

#### There two problem formulations:

- Find the most likely haplotype (MLH) configuration for each genotype  $\mathbf{g} \in G$ .
- Find a set of haplotypes by some parsimony rule





### Several versions for haplotype inference (continue)

#### Parsimony haplotype inference problem:

- MRG problem Based on Clark's inference rule (Clark, 1990), Gusfield D., 2003 employed a graph-theoretic view to express and analyze the inference problem.
- Inference by pure parsimony (**HIPP**): Find a cardinality-smallest set H such that for each  $g \in G$ , there is a haplotype configuration made by two sequences in H.



### The complexity of these problems

- The MLH (most likely haplotype) model is solved by stochastic methods, such as Markov chain model, maximum likelihood estimation.
- The MRG ( model is proved NP-hard.
- The **HIPP** model is also an NP-hard problem.

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### Algorithms

- Algorithms for MLH (most likely haplotype)
  - A partition-ligation algorithm (an exhaustive search approach) is used to find the most probable haplotypes.
  - A dynamic programming algorithm based on the Markov chain framework is developed in Zhang J.-H et al., 2005.

### Algorithms (continue)

- Algorithms for the deterministic parsimony rule:
  - The **MRG** model by Gusfield, 2003 can be exactly formulated as an integer linear programming.
  - Algorithms for the HIPP problem are still in development
    - A branch-and-bound method by Wang and Xu, 2003.
    - A tree-grow method with complexity of  $O(m^2n)$  by Li, Zhang and Chen, 2005.

#### Basic ideas of **TGM**

 Resolve columns, one by one, of the genotype matrix G by haplotype fragments; Let

$$\mathbf{G}=(\hat{\mathbf{g}}_1,\hat{\mathbf{g}}_2,\cdots,\hat{\mathbf{g}}_n)$$

Then **TGM** solves  $(\hat{\mathbf{g}}_1), (\hat{\mathbf{g}}_1, \hat{\mathbf{g}}_2), \cdots, \mathbf{G}$  successively.

 Extend the haplotype fragments in growing length by keeping all corresponding genotype fragments resolved;

### Basic ideas of **TGM** (continued

- Use a growing tree to represent the haplotype fragments developing. Making a haplotype fragment one site longer means to add a branch to the existing tree and for resolving the corresponding longer genotype fragment.
- Carefully add a new branch to reach the parsimony effect, that is for each  $(\hat{\mathbf{g}}_1, \cdots, \hat{\mathbf{g}}_k)$ ,  $k = 1, 2, \cdots, n$ , the tree solves it is the **smallest** one.



#### Initialization:

Input an  $m \times n$  **G**. Set a root node  $v_{01}$ ,  $v_{01} = \{1, \dots, m\}$ . Set f(i) = false, for every  $i = 1, \dots, m$ . Let j = 0, and go to step 1.

**Step 1** Resolve submatrix G[1, j + 1]. Suppose that there are p nodes  $v_{j1}, \dots, v_{jk}, \dots, v_{jp}$  in the j-th layer of the growing-tree representing p distinct haplotype fragments resolving G[1, j].  $v_{j1}, \dots, v_{jp}$  also represent corresponding index sets. Do Substeps 1.1 and 1.2 depicted below.

Substep 1.1 For each  $1 \le k \le p$ , and each i,  $(1 \le i \le m)$ , if  $i \in v_{jk}$ , resolve the i-th genotype fragment in  $\mathbf{G}[1,j]$  when i satisfies either of the following two conditions:

Condition 1:  $g_{i,j+1} \neq 2$ ;

**Condition 2**:  $g_{i,j+1} = 2$ , and f(i) = false.

**Otherwise**, record the i in a set I(j); and record  $v_{jk}$  in a node set  $T_{ij}$ , where  $T_{ij}$  is a set of the j-th layer nodes that include node i.

- if  $g_{i,j+1} = 0$ , then add a branch 0 to  $v_{jk}$  when there is no branch 0 growing from  $v_{jk}$ ; add i to  $v_{(j+1)}$ , which is connected to the node  $v_{jk}$  by the existing or just added branch 0.
- if  $g_{i,j+1} = 1$ , then add a branch 1 to  $v_{jk}$  when there is no branch 1 growing from  $v_{jk}$ ; add i to  $v_{(j+1)}$ , which is connected to  $v_{jk}$  by the existing or just added branch 1.
- if  $g_{i,j+1} = 2$  and f(i) = false, then add a branch 0 or 1, or both branches 0 and 1 or nothing to  $v_{jk}$  according to the following cases: only one type exists, no branch exists, or two types of branches exist. Add i into both index sets of the (j+1)-th layer nodes connected to node  $v_{jk}$ , set f(i) = true.

Substep 1.2 For  $i \in I(j)$ , suppose  $T_{ij} = \{v_{jk_1}, v_{jk_1}\}$ , i belongs to  $v_{jk_1}$  and  $v_{jk_2}$ . Check whether there are two different branch types growing separately from  $v_{jk_1}$  and  $v_{jk_2}$ .

- **1** If there are no such two different types of branches, then add a proper type of branch to  $v_{jk_1}$  or  $v_{jk_2}$ , or add two different types, one to  $v_{jk_1}$  while the other to  $v_{jk_2}$ .
- ② Choose a pair of different types, one growing from  $v_{jk_1}$ , the other from  $v_{jk_2}$ . Add i into both index sets of the (j+1)-th layer which are connected to  $v_{jk_1}$  or  $v_{jk_2}$  by one of the chosen branches.

**Step 2** If j+1 < n, set j := j+1, and return to Step 1. Otherwise assemble haplotypes as follows. Trace each path from  $v_{01}$  to every node in the n-th layer. The sequence of branch type indices (0 or 1) of the path gives a haplotype, which can be used to resolve the genotypes whose indices belong to the corresponding node in the n-th layer. All the haplotypes corresponding to the n-th layer nodes consist of  $\mathcal{H}(\mathbf{G})$ .

#### An Example

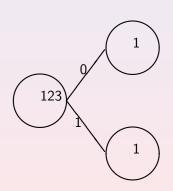
Given a genotype matrix

$$\mathbf{G} = \begin{pmatrix} 2 & 2 & 0 \\ 2 & 0 & 2 \\ 0 & 2 & 2 \end{pmatrix} \tag{1}$$

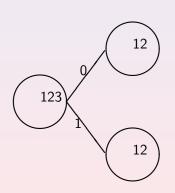
The columns are

$$\hat{\mathbf{g}}_1 = \begin{pmatrix} 2 \\ 2 \\ 0 \end{pmatrix}, \ \hat{\mathbf{g}}_2 = \begin{pmatrix} 2 \\ 0 \\ 2 \end{pmatrix}, \ \hat{\mathbf{g}}_3 = \begin{pmatrix} 0 \\ 2 \\ 2 \end{pmatrix} \tag{2}$$

Set f(1) = False, f(2) = False, f(3) = False

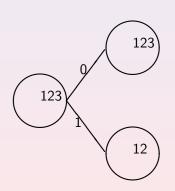


Set 
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,  $f(2) = False$ ,  $f(3) = False$ 

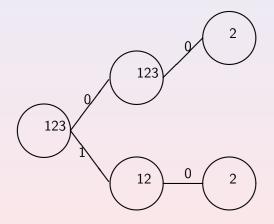


Set 
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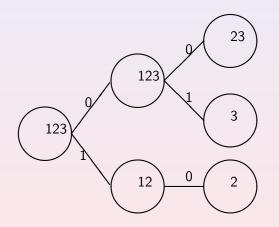
Set 
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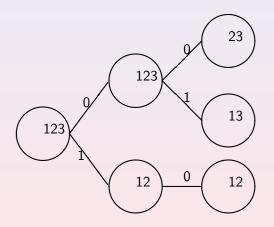
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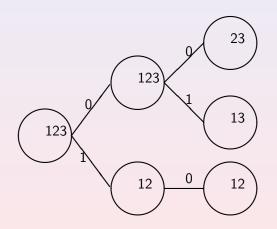
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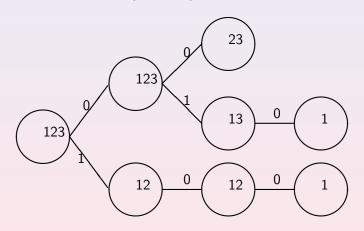
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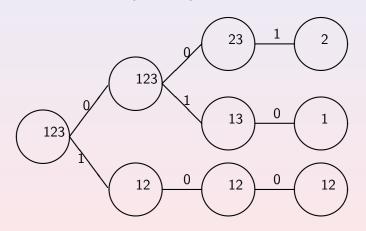
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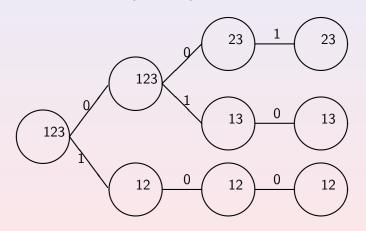
Set 
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Set 
$$f(1) = Ture$$
,  $f(2) = Ture$ ,  $f(3) = Ture$ 



Set 
$$f(1) = Ture$$
,  $f(2) = Ture$ ,  $f(3) = Ture$ 



Set 
$$f(1) = Ture$$
,  $f(2) = Ture$ ,  $f(3) = Ture$ 

### Complexity and Convergence Rate

- A convergence analysis and an error bound is given on the base of the microstructure discussion of the genotype matrix G.
- **Theorem 1**. Given an  $m \times n$  genotype matrix **G**, the computational complexity of **TGM** is  $O(m^2n)$ .





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#### Evaluation criteria

 Reconstruction error rate (ER): to measure the proportion of genotypes which are resolved by a wrong pair of haplotypes.



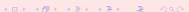


#### Data sets

# 4 experiments

- 18 genotypes coming from  $\beta_1 AR$  gene
- 11 genotypes coming from ACE gene
- Simulated genotypes based on Maize data
- Simulated genotypes and haplotypes





# Experiment result 1 — on $\beta_1AR$ data

- The resolution of every genotype obtained by TGM is exactly the same as the real ones, that is, with an ER 0.
- The total running time is 0.016 second, very efficient in contrast to over a minute for HAPAR (Niu, et.al., 2001) and over ten minutes for PHASE (Stephens, et.al., 2001).

## Experiment result 2 — on ACE data

- **TGM** obtained 13 haplotypes with 9 correct haplotypes that resolve 9 out of the 11 genotypes correctly with an ER 0.182. It is is better than or at least equal to widely used existing programs,
  - HAPAR with RER 0.273.
  - **Haplotyper** with **RER** 0.182,
  - **HAPINFERX** with **RER** 0.273, **PHASE** with **RER** 0.273.

#### Experiment result 3 — on Maize data

Generate a sample of *n* genotypes each of which is conflated by two randomly picked haplotypes in a set.

• **TGM** correctly resolves all genotypes for sample sizes from 4 to 10, and behaves best among five programs.

Sample size	TGM	HAPAR	Haplotyper	HAPINFERX	PHASE
3	0.02	0.51	0.47	0.86	0.53
4	0	0.10	0.14	0.64	0.15
7	0	0.05	0.05	0.43	0.07
10	0	0	0	0.28	0

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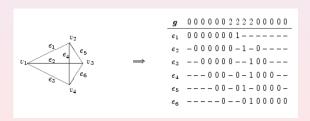


## The hybrid haplotyping problem

- The **MEC/GI** is an **MEC** (*Minimum Error Correction*) with added genotype information:
- Given a SNP matrix  $\mathbf{W} = (w_{ij})$  and a genotype  $\mathbf{g}$ , correct minimum number of elements (0 into 1 or vice versa) so that the resulting matrix is feasible and  $\mathbf{g}$ -compatible, i.e., the corrected SNP fragments will determine a pair of haplotypes that is compatible with g.

## The hybrid haplotyping problem (continue)

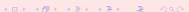
- The MEC/GI problem can be described as an integer linear programming.
- The MEC/GI problem is NP-hard by reduction from MAX-CUT:



# The hybrid haplotyping problem (continue)

- A dynamic programming algorithm is given for a special case to illustrate the problem structure.
- A feed-forward neural network is proposed for the general case in Zhang X.-S et al., 2005.





# NN Algorithms for MEC/GI

Using 2 to denote the wild homogenous allele, -2 to denote the mutant homogenous allele, and 0 to denote the heterozygous allele, then a genotype is a vector on  $\{2, -2, 0\}$  while a haplotype is a vector on  $\{-1, 1\}$ . Let

$$\mathbf{x}_i = (x_{i1}, x_{i2}, \cdots, x_{in}), i = 1, 2, \cdots, m$$

be m SNP fragments.



# NN Algorithms for MEC/GI

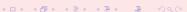
The **MEC/GI** problem is to find a pair of haplotypes  $(\mathbf{h}_1, \mathbf{h}_2)$  to minimize

$$\sum_{k=1}^{n} (h_{1k} + h_{2k} - g_k)^2$$

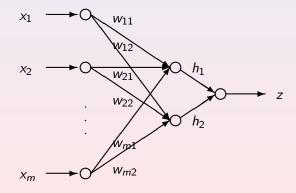
and

$$\sum_{\mathbf{x}_i \in X_1} \mathit{HD}(\mathbf{h}_1, \mathbf{x}_i) + \sum_{\mathbf{x}_i \in X_2} \mathit{HD}(\mathbf{h}_2, \mathbf{x}_i)$$





#### The structure of a feed-forward neural network







# The objectives that neural network learns

• For the neurons corresponding to  $\mathbf{h}_1$  ( $\mathbf{h}_2$ ) in the second layer, the network learns to minimize the following error function between  $\mathbf{h}_1$  ( $\mathbf{h}_2$ ) and the SNP fragments in  $X_1$  ( $X_2$ ):

$$f_{21} = \sum_{\mathbf{x}_i \in X_1} \sum_{k=1}^n (h_{1k} - x_{ik})^2 |x_{ik}|$$

$$f_{22} = \sum_{\mathbf{x}:\in X_2} \sum_{k=1}^n (h_{2k} - x_{ik})^2 |x_{ik}|$$



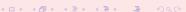


# The objectives that neural network learns

 The objective that the third layer adjusts to is to minimize the following error function between the output of the third layer and the original genotype:

$$f_1 = \sum_{k=1}^{n} (h_{1k} + h_{2k} - g_k)^2$$





### Details of the algorithm

Set parameter values  $L_1, L_2, \rho, \lambda$  and  $\varepsilon$ . Randomly initiate weight matrix W(0) with  $w_{il} \in [0,1], i=1,\cdots,m,\ l=1,2.$  t=0.

- Obtain a pair of two haplotypes  $(h_1, h_2)$  according to the current weight matrix;
- ② Classify all SNP fragments using  $(h_1, h_2)$  and calculate the derivatives  $\nabla_{w_{i1}} f_{11}$ ,  $\nabla_{w_{i2}} f_{12}$ ,  $\nabla_{w_{i1}} f_{2}$ ,  $\nabla_{w_{i2}} f_{2}$ ,  $i = 1, 2, \cdots, m$ ;

## Details of the algorithm

- 1
- 2
- **3** Update the current weight matrix W(t) by using the formulae

$$w_1(t+1) = w_1(t) - \rho(L_1 \nabla_{w_1} f_1 + L_2 \nabla_{w_1} f_{21}),$$
  

$$w_2(t+1) = w_2(t) - \rho(L_1 \nabla_{w_2} f_1 + L_2 \nabla_{w_2} f_{22}),$$

where  $\rho$  is step length and  $L_1$ ,  $L_2$  are parameters;

• Repeat Step 1 to Step 3 until no change occurs for  $w_{il}$ ,  $i = 1, 2, \dots, m$ , l = 1, 2, i.e.  $||W(t+1) - W(t)|| < \varepsilon$ .

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#### Data sets and evaluation criteria

#### Data sets:

100 pairs of simulated haplotypes,

$$s = 0.5, \ s = 0$$

- 8 pairs of haplotypes coming from ACE gene
- 129 pairs of haplotypes coming from 5q31 gene





#### Data sets and evaluation criteria

#### Evaluation criteria:

• Haplotype reconstruction rate, Set  $r_{ij} = HD(\mathbf{h}_i, \hat{\mathbf{h}}_j), i = 1, 2, j = 1, 2$ . Define haplotype reconstruction rate **RR**:

$$\mathbf{R}R(\mathbf{h},\hat{\mathbf{h}}) = 1 - \frac{\min\{r_{11} + r_{22}, r_{12} + r_{21}\}}{2n}$$

The number of Error Correction

$$E(P) = \sum_{i=1}^{2} \sum_{f \in C_i} HD(f, \mathbf{h}_i).$$



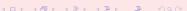


## Experiment result 1 — on simulation data set

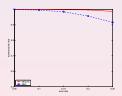
Table: The comparative results of the MEC/GI model and the MEC model

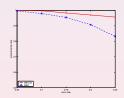
error rate	S	=0.5	s=0.0	
	MEC	MEC/GI	MEC	MEC/GI
0.05	0.941	1.000	0.965	0.996
0.1	0.904	0.969	0.950	0.984
0.15	0.863	0.969	0.890	0.946
0.2	0.786	0.908	0.834	0.922
0.25	0.763	0.863	0.766	0.830

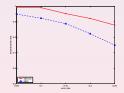




### Experiment result 2 — on ACE data set

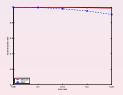


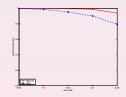


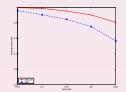




## Experiment result 2 — on 5q31 data set









# Thank you

